

ELITE IGCSE MATHEMATICS
EXPERIENCE NOTES

Mechanics 1 Strategy Booklet

Complete strategy booklet collected from the individual topic notes, with hard-variant coverage preserved.

MECHANICS 1 STRATEGY BOOKLET · WME01 · COMPLETE

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DR ESLAM AHMED · CAIRO UNIVERSITY FACULTY OF ENGINEERING

Booklet Map

This complete booklet collects all Mechanics 1 individual strategy notes into one printable file. The individual topic PDFs remain available separately.

COURSE EVIDENCE Topics: 10. Topic-note pages: 110. The combined PDF also includes this cover and map.

NO	TOPIC	PAGES	STRATEGIES
01	Quantities, Units & Modelling	11	UNIT: Unit Discipline MODEL: Modelling Words WEIGH: Mass And Weight ROUND: Accuracy Control
02	Working with Vectors	11	COMP: Component Form RESULT: Resultant And Bearing PATH: Position Path CLOSE: Closest Distance
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10	Moments	11	PIVOT: Choose Pivot REACT: Find Reactions TILT: Tilting Limit CENTRE: Centre Of Mass

ELITE IGCSE MATHEMATICS
EXPERIENCE NOTES

Quantities, Units & Modelling

Mechanics begins by naming the quantity, unit, and model before doing any algebra.

QUANTITIES, UNITS & MODELLING · M1 · 01

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The Map

This strategy booklet was mined from the local Mechanics 1 topic problem/answer PDFs, Dr Eslam's source notes, and the WME01 website answer bank. Mechanics questions become reliable when the diagram, sign convention, and equation family are chosen first.

01 UNIT: Unit Discipline

TRIGGER *units, modelling, dimensions*

02 MODEL: Modelling Words

TRIGGER *particle, light string, smooth plane*

03 WEIGH: Mass And Weight

TRIGGER *mass, weight, g*

04 ROUND: Accuracy Control

TRIGGER *show that, 3 significant figures*

BANK EVIDENCE Local pages: 29 problem, 46 answer, 15 notes. Website primary entries: 0. Website linked entries: 42.

01 UNIT: Unit Discipline

TRIGGER *units, modelling, dimensions*

BECOMES Convert and carry units before substituting.

FIRST LINE TO WRITE

$$\text{quantity} = \text{number} \times \text{unit}$$

SIMPLEST STRATEGY

1. Underline the quantity.
2. Name the unit.
3. Insert conversions.
4. Test the final unit.

WORKED MODEL

$$\mathbf{I} \quad 72 \text{ km h}^{-1} = 20 \text{ m s}^{-1}.$$

HARD VARIANTS

1. Convert before using SUVAT or $F = ma$.
2. For compound units, convert every component of the unit.
3. Check if the question fixes $g = 9.8$ or allows exact g .

— BOTTOM LINE

Units are part of the answer, not decoration.

02 MODEL: Modelling Words

TRIGGER *particle, light string, smooth plane*

BECOMES Translate each modelling word into a mathematical permission.

FIRST LINE TO WRITE

| $\text{smooth} \Rightarrow F = 0$

SIMPLEST STRATEGY

1. Mark the modelling word.
2. Output its meaning.
3. Draw what remains.
4. Exclude ignored effects.
5. Link to the equation.

WORKED MODEL

| Light string means the tension is the same throughout that string.

HARD VARIANTS

1. Smooth means no friction, not no normal reaction.
2. Light means no weight for that string or rod only.
3. Inextensible means connected particles have the same acceleration magnitude.

— BOTTOM LINE

A modelling word is an instruction for the diagram.

Practice Page: MODEL

QUESTION TYPE Model assumptions

State the modelling assumption that lets air resistance be ignored.

COMMON TRAP Using a force that the model says is absent.

03 WEIGH: Mass And Weight

TRIGGER *mass, weight, g*

BECOMES Convert mass into weight only when a force is needed.

FIRST LINE TO WRITE

$$W = mg$$

SIMPLEST STRATEGY

1. Write $W = mg$.
2. Enter mass in kg.
3. Insert g .
4. Give force in newtons.
5. Hold exact g if requested.

WORKED MODEL

▮ A 5 kg particle has weight 5g N, or 49 N if $g = 9.8$.

HARD VARIANTS

1. Use mg in moments and dynamics, not just m .
2. If answers use g , do not replace it unless asked.
3. For grams, convert to kg before multiplying by g .

— BOTTOM LINE

Mass is measured in kg; weight is a force.

Practice Page: WEIGH

QUESTION TYPE Mass/weight

Find the weight of a 3.2 kg particle.

COMMON TRAP Writing kilograms as a force.

04 ROUND: Accuracy Control

TRIGGER *show that, 3 significant figures*

BECOMES Keep exact working, round only the final statement.

FIRST LINE TO WRITE

| exact first, rounded last

SIMPLEST STRATEGY

1. Retain exact fractions or radicals.
2. Only round at the end.
3. Use the requested accuracy.
4. Name units.
5. Do a reasonableness check.

WORKED MODEL

| $\sqrt{52} = 7.211\dots$, so 7.21 to 3 s.f.

HARD VARIANTS

1. For show-that answers, keep enough figures to support the printed value.
2. Bearings need three digits.
3. Do not mix exact g and decimal g in the same final line.

— BOTTOM LINE

Rounding early moves the answer.

Quick Recognition Table

WHEN YOU SEE	FIRST LINE TO WRITE
units, modelling, dimensions	quantity = number \times unit
particle, light string, smooth plane	smooth $\Rightarrow F = 0$
mass, weight, g	$W = mg$
show that, 3 significant figures	exact first, rounded last

Hard Variant Checklist

STRATEGY	CHECK BEFORE FINAL ANSWER
UNIT: Unit Discipline	Convert before using SUVAT or $F = ma$. For compound units, convert every component of the unit. Check if the question fixes $g = 9.8$ or allows exact g .
MODEL: Modelling Words	Smooth means no friction, not no normal reaction. Light means no weight for that string or rod only. Inextensible means connected particles have the same acceleration magnitude.
WEIGH: Mass And Weight	Use mg in moments and dynamics, not just m . If answers use g , do not replace it unless asked. For grams, convert to kg before multiplying by g .
ROUND: Accuracy Control	For show-that answers, keep enough figures to support the printed value. Bearings need three digits. Do not mix exact g and decimal g in the same final line.

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Working with Vectors

Vector questions become simple after choosing components and keeping direction signs visible.

WORKING WITH VECTORS · M1 · 02

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The Map

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01 COMP: Component Form

TRIGGER *bearing, magnitude, vector components*

02 RESULT: Resultant And Bearing

TRIGGER *resultant force, magnitude, bearing*

03 PATH: Position Path

TRIGGER *position vector, velocity vector*

04 CLOSE: Closest Distance

TRIGGER *minimum distance, nearest approach*

BANK EVIDENCE Local pages: 23 problem, 46 answer, 162 notes. Website primary entries: 27. Website linked entries: 42.

01 COMP: Component Form

TRIGGER *bearing, magnitude, vector components*

BECOMES Resolve the vector into i and j components.

FIRST LINE TO WRITE

$$\mathbf{v} = (v_E)\mathbf{i} + (v_N)\mathbf{j}$$

SIMPLEST STRATEGY

1. Choose east/north axes.
2. Obtain the reference angle.
3. Multiply by sine/cosine.
4. Place signs by quadrant.

WORKED MODEL

▮ A speed 40 on bearing 150° is $20\mathbf{i} - 20\sqrt{3}\mathbf{j}$.

HARD VARIANTS

1. East component uses sine of the bearing; north uses cosine.
2. Check signs from the quadrant, not from memory.
3. For angles from the i -axis, the sine/cosine roles change.

— BOTTOM LINE

Bearings are measured clockwise from north.

02 RESULT: Resultant And Bearing

TRIGGER *resultant force, magnitude, bearing*

BECOMES Add components, then find magnitude and direction.

FIRST LINE TO WRITE

$$\mathbf{R} = \sum \mathbf{F}, \quad |\mathbf{R}| = \sqrt{x^2 + y^2}$$

SIMPLEST STRATEGY

1. Resolve every vector.
2. Enter signs.
3. Sum components.
4. Use Pythagoras.
5. Locate quadrant.
6. Turn angle into bearing.

WORKED MODEL

| $\mathbf{R} = -4\sqrt{3}\mathbf{i} - 14\mathbf{j}$ points south-west.

HARD VARIANTS

1. Bearings must be written as three digits.
2. If the vector is west/south, add the reference angle to 180° or 360° correctly.
3. Use exact components until the final angle.

— BOTTOM LINE

A bearing answer must match the quadrant.

03 PATH: Position Path

TRIGGER *position vector, velocity vector*

BECOMES Build position as start plus velocity times time.

FIRST LINE TO WRITE

$$\mathbf{r} = \mathbf{r}_0 + t\mathbf{v}$$

SIMPLEST STRATEGY

1. Place the initial vector.
2. Add velocity times time.
3. Tidy i and j components.
4. Handle units of time.

WORKED MODEL

▮ $\mathbf{r} = (60 - 20t)\mathbf{i}$ for motion west from $60\mathbf{i}$.

HARD VARIANTS

1. Use the time unit matching the velocity unit.
2. Meeting means both components are equal at the same time.
3. Due north/south/east/west means one component is fixed.

— BOTTOM LINE

Position vector is a moving address.

04 CLOSE: Closest Distance

TRIGGER *minimum distance, nearest approach*

BECOMES Minimise distance squared.

FIRST LINE TO WRITE

$$d^2 = x(t)^2 + y(t)^2$$

SIMPLEST STRATEGY

1. Create separation vector.
2. Length squared.
3. Open the quadratic.
4. Square complete or use vertex.
5. Evaluate distance.

WORKED MODEL

$$(t - 4)^2 + (5 - t)^2 = 2(t - 4.5)^2 + 0.5.$$

HARD VARIANTS

1. Keep $d^2 \geq 0$; the minimum distance is not the minimum squared value unless square-rooted.
2. Reject a minimum time outside the allowed time interval.
3. For two particles, use one separation vector, not two separate distances.

— BOTTOM LINE

Minimise d^2 , then square-root at the end.

Quick Recognition Table

WHEN YOU SEE	FIRST LINE TO WRITE
bearing, magnitude, vector components	$\mathbf{v} = (v_E)\mathbf{i} + (v_N)\mathbf{j}$
resultant force, magnitude, bearing	$\mathbf{R} = \sum \mathbf{F}, \quad \mathbf{R} = \sqrt{x^2 + y^2}$
position vector, velocity vector	$\mathbf{r} = \mathbf{r}_0 + t\mathbf{v}$
minimum distance, nearest approach	$d^2 = x(t)^2 + y(t)^2$

Hard Variant Checklist

STRATEGY	CHECK BEFORE FINAL ANSWER
COMP: Component Form	East component uses sine of the bearing; north uses cosine. Check signs from the quadrant, not from memory. For angles from the i -axis, the sine/cosine roles change.
RESULT: Resultant And Bearing	Bearings must be written as three digits. If the vector is west/south, add the reference angle to 180° or 360° correctly. Use exact components until the final angle.
PATH: Position Path	Use the time unit matching the velocity unit. Meeting means both components are equal at the same time. Due north/south/east/west means one component is fixed.
CLOSE: Closest Distance	Keep $d^2 \geq 0$; the minimum distance is not the minimum squared value unless square-rooted. Reject a minimum time outside the allowed time interval. For two particles, use one separation vector, not two separate distances.

ELITE IGCSE MATHEMATICS
EXPERIENCE NOTES

Kinematics Graphs

Graph questions ask for gradients, areas, and clean piecewise stories.

KINEMATICS GRAPHS · M1 · 03

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The Map

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01 GRAD: Gradient Means Acceleration

TRIGGER *velocity-time graph gradient*

02 AREA: Area Means Displacement

TRIGGER *area under velocity-time graph*

03 PIECE: Piecewise Motion

TRIGGER *multi-stage graph*

04 SKETCH: Sketch From Words

TRIGGER *draw velocity-time graph*

BANK EVIDENCE Local pages: 59 problem, 86 answer, 17 notes. Website primary entries: 12. Website linked entries: 17.

01 GRAD: Gradient Means Acceleration

TRIGGER *velocity-time graph gradient*

BECOMES Acceleration is the gradient of the velocity-time graph.

FIRST LINE TO WRITE

$$a = \frac{\Delta v}{\Delta t}$$

SIMPLEST STRATEGY

1. Get two points.
2. Rise is velocity change.
3. Across is time change.
4. Divide with sign.

WORKED MODEL

▮ A fall from 12 to 4 in 2 s gives $a = -4 \text{ m s}^{-2}$.

HARD VARIANTS

1. Curved graphs need tangent gradients.
2. Use signs: below the time axis means negative velocity.
3. Acceleration changes on each different line segment.

— BOTTOM LINE

Downward graph slope means negative acceleration.

02 AREA: Area Means Displacement

TRIGGER *area under velocity-time graph*

BECOMES Displacement is signed area under the velocity-time graph.

FIRST LINE TO WRITE

$$s = \text{area under } v-t$$

SIMPLEST STRATEGY

1. Add simple shapes.
2. Record sign above or below axis.
3. Evaluate each area.
4. Aggregate displacement.

WORKED MODEL

▮ A triangle of base 6, height 10 has area 30.

HARD VARIANTS

1. For total distance, add absolute areas.
2. If the graph crosses the axis, split the area at the crossing.
3. Use trapeziums for sloping segments with two non-zero velocities.

— BOTTOM LINE

Area gives displacement, not always distance.

03 PIECE: Piecewise Motion

TRIGGER *multi-stage graph*

BECOMES Treat each graph segment as its own motion stage.

FIRST LINE TO WRITE

| stage 1 + stage 2 + ...

SIMPLEST STRATEGY

1. Partition at corners.
2. Identify each shape.
3. Evaluate gradients/areas.
4. Combine carefully.
5. Explain the motion in words.

WORKED MODEL

▮ Constant velocity is a horizontal line; constant acceleration is a straight sloping line.

HARD VARIANTS

1. Rest is $v = 0$, not necessarily $s = 0$.
2. Negative velocity means motion in the opposite direction.
3. Average speed needs total distance divided by total time.

— BOTTOM LINE

Every corner starts a new rule.

04 SKETCH: Sketch From Words

TRIGGER *draw velocity-time graph*

BECOMES Convert each phrase into a graph feature.

FIRST LINE TO WRITE

| accelerates uniformly \Rightarrow straight sloping line

SIMPLEST STRATEGY

1. Start at the given velocity.
2. Keep axes labelled.
3. Encode each phrase.
4. Time-scale the segments.
5. Check areas if distance is given.
6. Hold units.

WORKED MODEL

| Uniform deceleration to rest is a straight line ending on the time axis.

HARD VARIANTS

1. If distance is given, area must match it.
2. If acceleration is greater, slope must be steeper.
3. Graph labels can earn marks even when scale is not perfect.

— BOTTOM LINE

The shape tells the motion.

Quick Recognition Table

WHEN YOU SEE	FIRST LINE TO WRITE
velocity-time graph gradient	$a = \frac{\Delta v}{\Delta t}$
area under velocity-time graph	$s = \text{area under } v-t$
multi-stage graph	stage 1 + stage 2 + ...
draw velocity-time graph	accelerates uniformly \Rightarrow straight sloping line

Hard Variant Checklist

STRATEGY	CHECK BEFORE FINAL ANSWER
GRAD: Gradient Means Acceleration	Curved graphs need tangent gradients. Use signs: below the time axis means negative velocity. Acceleration changes on each different line segment.
AREA: Area Means Displacement	For total distance, add absolute areas. If the graph crosses the axis, split the area at the crossing. Use trapeziums for sloping segments with two non-zero velocities.
PIECE: Piecewise Motion	Rest is $v = 0$, not necessarily $s = 0$. Negative velocity means motion in the opposite direction. Average speed needs total distance divided by total time.
SKETCH: Sketch From Words	If distance is given, area must match it. If acceleration is greater, slope must be steeper. Graph labels can earn marks even when scale is not perfect.

ELITE IGCSE MATHEMATICS
EXPERIENCE NOTES

Constant Acceleration in 1D

One-dimensional motion is a sign convention plus the right SUVAT equation.

CONSTANT ACCELERATION IN 1D · M1 · 04

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The Map

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01 SUVAT: Choose The Missing Letter

TRIGGER *constant acceleration, u, v, a, s, t*

02 SIGN: Sign Convention

TRIGGER *opposite directions, deceleration*

03 MEET: Meeting Motions

TRIGGER *two particles meet, overtake*

04 VERT: Vertical Gravity

TRIGGER *thrown up, falling, maximum height*

BANK EVIDENCE Local pages: 22 problem, 41 answer, 12 notes. Website primary entries: 16. Website linked entries: 66.

01 SUVAT: Choose The Missing Letter

TRIGGER *constant acceleration, u, v, a, s, t*

BECOMES List knowns and choose the equation missing the unwanted letter.

FIRST LINE TO WRITE

|

u, v, a, s, t

SIMPLEST STRATEGY

1. Select positive direction.
2. Underline known quantities.
3. Vacant letter is avoided.
4. Apply the matching equation.
5. Tidy units.

WORKED MODEL

| If u, a, t are known and s is needed, use $s = ut + \frac{1}{2}at^2$.

HARD VARIANTS

1. Only use SUVAT when acceleration is constant.
2. If direction changes, split the motion at $v = 0$.
3. Convert units before writing the equation.

— BOTTOM LINE

SUVAT is a selection problem first.

02 SIGN: Sign Convention

TRIGGER *opposite directions, deceleration*

BECOMES Choose one positive direction and make all quantities obey it.

FIRST LINE TO WRITE

| up/right/forward is positive

SIMPLEST STRATEGY

1. Set the positive direction.
2. Insert signs for u, v, a, s .
3. Guard against word signs.
4. Note final direction.

WORKED MODEL

| If upward is positive, gravity gives $a = -g$.

HARD VARIANTS

1. Displacement can be negative even when distance is positive.
2. Final velocity sign tells direction.
3. Do not change sign convention halfway through a part.

— BOTTOM LINE

A negative answer usually means opposite to your chosen direction.

03 MEET: Meeting Motions

TRIGGER *two particles meet, overtake*

BECOMES Write each position from the same origin and set them equal.

FIRST LINE TO WRITE

$$s_A = s_B$$

SIMPLEST STRATEGY

1. Model both positions.
2. Equalise positions.
3. Extract valid time.
4. Translate time into the asked result.

WORKED MODEL

$$s_A = 2t, s_B = 20 - t^2, \text{ so meeting means } 2t = 20 - t^2.$$

HARD VARIANTS

1. Use a common origin and sign convention.
2. Reject negative times.
3. If they start at different times, adjust the time variable.

— BOTTOM LINE

Meeting is same place at same time.

04 VERT: Vertical Gravity

TRIGGER *thrown up, falling, maximum height*

BECOMES Use $a = -g$ if upward is positive and split at the top if needed.

FIRST LINE TO WRITE

$$v = 0 \quad \text{at greatest height}$$

SIMPLEST STRATEGY

1. Vertical positive direction.
2. Enter $a = -g$.
3. Recognise top has $v = 0$.
4. Time/height from SUVAT.

WORKED MODEL

At greatest height, $v = 0$, so $0 = u^2 - 2gh$.

HARD VARIANTS

1. Total flight may need two stages if launch and landing heights differ.
2. Use $g = 9.8$ only if numerical answers are wanted.
3. Velocity can be negative on the way down.

— BOTTOM LINE

The top of the flight has zero velocity, not zero acceleration.

Quick Recognition Table

WHEN YOU SEE	FIRST LINE TO WRITE
constant acceleration, u, v, a, s, t	u, v, a, s, t
opposite directions, deceleration	up/right/forward is positive
two particles meet, overtake	$s_A = s_B$
thrown up, falling, maximum height	$v = 0$ at greatest height

Hard Variant Checklist

STRATEGY	CHECK BEFORE FINAL ANSWER
SUVAT: Choose The Missing Letter	Only use SUVAT when acceleration is constant. If direction changes, split the motion at $v = 0$. Convert units before writing the equation.
SIGN: Sign Convention	Displacement can be negative even when distance is positive. Final velocity sign tells direction. Do not change sign convention halfway through a part.
MEET: Meeting Motions	Use a common origin and sign convention. Reject negative times. If they start at different times, adjust the time variable.
VERT: Vertical Gravity	Total flight may need two stages if launch and landing heights differ. Use $g = 9.8$ only if numerical answers are wanted. Velocity can be negative on the way down.

ELITE IGCSE MATHEMATICS
EXPERIENCE NOTES

Constant Acceleration in 2D

Two-dimensional motion is two one-dimensional motions sharing the same time.

CONSTANT ACCELERATION IN 2D · M1 · 05

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01 SPLIT: Split Axes

TRIGGER *2D constant acceleration*

02 PROJ: Projectile Equation

TRIGGER *projectile, trajectory*

03 TIME: Flight Time

TRIGGER *hits ground, returns to level*

04 REL: Relative Position

TRIGGER *two moving particles in 2D*

BANK EVIDENCE Local pages: 19 problem, 39 answer, 4 notes. Website primary entries:
1. Website linked entries: 22.

01 SPLIT: Split Axes

TRIGGER *2D constant acceleration*

BECOMES Resolve into independent i and j equations.

FIRST LINE TO WRITE

$$\mathbf{r} = \mathbf{r}_0 + \mathbf{u}t + \frac{1}{2}\mathbf{a}t^2$$

SIMPLEST STRATEGY

1. Separate i and j .
2. Place the same t in both.
3. List known components.
4. Insert acceleration.
5. Tie answers back together.

WORKED MODEL

$$\mathbf{r} = (2 + 3t)\mathbf{i} + (5 - 4.9t^2)\mathbf{j}.$$

HARD VARIANTS

1. Horizontal acceleration is zero in projectile motion unless stated.
2. Use vector components for velocity too.
3. Keep units consistent in both axes.

— BOTTOM LINE

The same time connects both axes.

Practice Page: SPLIT

QUESTION TYPE Vector kinematics

Write the position vector for a particle with $\mathbf{u} = 3\mathbf{i} + 4\mathbf{j}$ under gravity.

COMMON TRAP Using different times in each component.

02 PROJ: Projectile Equation

TRIGGER *projectile, trajectory*

BECOMES Use horizontal motion to express t , then substitute into vertical motion.

FIRST LINE TO WRITE

$$x = u_x t, \quad y = u_y t - \frac{1}{2} g t^2$$

SIMPLEST STRATEGY

1. Pick horizontal equation.
2. Rearrange for t .
3. Output vertical equation.
4. Join them by substitution.

WORKED MODEL

▮ If $x = ut$, then $t = x/u$ and $y = u_y(x/u) - \frac{1}{2}g(x/u)^2$.

HARD VARIANTS

1. If launch point is not origin, include initial x, y .
2. Horizontal velocity stays constant only when no horizontal acceleration.
3. Domain matters: the path equation may extend beyond the physical flight.

— BOTTOM LINE

Trajectory comes from eliminating time.

Practice Page: PROJ

QUESTION TYPE Projectile path

Find the equation of the path of a projectile.

COMMON TRAP Trying to use one SUVAT equation for both axes.

03 TIME: Flight Time

TRIGGER *hits ground, returns to level*

BECOMES Use the vertical displacement condition to find time.

FIRST LINE TO WRITE

$$y(t) = 0 \quad \text{or given height}$$

SIMPLEST STRATEGY

1. Take the vertical equation.
2. Insert final height.
3. Make a quadratic if needed.
4. Exclude the wrong root.

WORKED MODEL

Returning to launch level gives $t = 0$ or $t = \frac{2u_y}{g}$.

HARD VARIANTS

1. If landing height differs, solve the full quadratic.
2. Check that a root lies after launch.
3. Use the time in horizontal motion to get range.

— BOTTOM LINE

The useful time is usually the non-zero positive root.

04 REL: Relative Position

TRIGGER *two moving particles in 2D*

BECOMES Subtract position vectors and minimise or solve components.

FIRST LINE TO WRITE

$$\vec{AB} = \mathbf{r}_B - \mathbf{r}_A$$

SIMPLEST STRATEGY

1. Read both position vectors.
2. Extract separation.
3. Link condition: meet, distance, due direction.

WORKED MODEL

■ Due east means the j -component of separation is zero.

HARD VARIANTS

1. Meet means both separation components are zero.
2. Closest distance uses separation squared.
3. Bearings from one object use the relative vector from that object.

— BOTTOM LINE

Relative position turns two particles into one vector.

Quick Recognition Table

WHEN YOU SEE	FIRST LINE TO WRITE
2D constant acceleration	$\mathbf{r} = \mathbf{r}_0 + \mathbf{u}t + \frac{1}{2}\mathbf{a}t^2$
projectile, trajectory	$x = u_x t, \quad y = u_y t - \frac{1}{2}gt^2$
hits ground, returns to level	$y(t) = 0$ or given height
two moving particles in 2D	$\vec{AB} = \mathbf{r}_B - \mathbf{r}_A$

Hard Variant Checklist

STRATEGY	CHECK BEFORE FINAL ANSWER
SPLIT: Split Axes	Horizontal acceleration is zero in projectile motion unless stated. Use vector components for velocity too. Keep units consistent in both axes.
PROJ: Projectile Equation	If launch point is not origin, include initial x, y . Horizontal velocity stays constant only when no horizontal acceleration. Domain matters: the path equation may extend beyond the physical flight.
TIME: Flight Time	If landing height differs, solve the full quadratic. Check that a root lies after launch. Use the time in horizontal motion to get range.
REL: Relative Position	Meet means both separation components are zero. Closest distance uses separation squared. Bearings from one object use the relative vector from that object.

ELITE IGCSE MATHEMATICS
EXPERIENCE NOTES

Forces

Force questions reward a clean diagram before any equation.

FORCES · M1 · 06

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The Map

This strategy booklet was mined from the local Mechanics 1 topic problem/answer PDFs, Dr Eslam's source notes, and the WME01 website answer bank. Mechanics questions become reliable when the diagram, sign convention, and equation family are chosen first.

01 FBD: Free Body Diagram

TRIGGER *forces on a particle*

02 RESOLVE: Resolve Forces

TRIGGER *force at angle, components*

03 EQUIL: Equilibrium Equations

TRIGGER *particle in equilibrium*

04 FRIC: Friction Limit

TRIGGER *rough plane, limiting friction*

BANK EVIDENCE Local pages: 26 problem, 52 answer, 12 notes. Website primary entries: 15. Website linked entries: 29.

01 FBD: Free Body Diagram

TRIGGER *forces on a particle*

BECOMES Draw only the forces acting on the body being studied.

FIRST LINE TO WRITE

$$\text{weight} = mg, \quad R \perp \text{surface}$$

SIMPLEST STRATEGY

1. Focus on one body.
2. Build all external forces.
3. Delete forces on other bodies.

WORKED MODEL

On a rough horizontal plane: mg down, R up, friction along the plane.

HARD VARIANTS

1. Tension pulls away from the particle along the string.
2. Normal reaction is perpendicular to the contact surface.
3. Friction opposes actual or impending motion.

— BOTTOM LINE

The diagram chooses the equations.

02 RESOLVE: Resolve Forces

TRIGGER *force at angle, components*

BECOMES Resolve every angled force along chosen axes.

FIRST LINE TO WRITE

$$F_x = F \cos \theta, \quad F_y = F \sin \theta$$

SIMPLEST STRATEGY

1. Rotate to useful axes.
2. Evaluate components.
3. Sign by direction.
4. Organise parallel/perpendicular equations.
5. Label units.
6. Verify with diagram.
7. End with resultant.

WORKED MODEL

▮ A 10 N force at 30° above horizontal has horizontal component $10 \cos 30^\circ$.

HARD VARIANTS

1. If the angle is to the vertical, swap sine/cosine roles.
2. On slopes, axes parallel/perpendicular to plane are usually best.
3. Keep exact trig until the final result.

— BOTTOM LINE

Resolve along the axes you will use.

03 EQUIL: Equilibrium Equations

TRIGGER *particle in equilibrium*

BECOMES Set resultant force to zero in each direction.

FIRST LINE TO WRITE

$$\sum F_x = 0, \quad \sum F_y = 0$$

SIMPLEST STRATEGY

1. Establish axes.
2. Quietly resolve.
3. Use zero resultant.
4. Isolate unknowns.
5. Label final forces.

WORKED MODEL

For equilibrium on a horizontal plane, $R = mg$ if no other vertical force acts.

HARD VARIANTS

1. Use simultaneous equations when two unknowns appear.
2. If three forces are in equilibrium, a triangle of forces may help.
3. Do not assume $R = mg$ when angled pulls are present.

— BOTTOM LINE

Equilibrium means no resultant force.

04 FRIC: Friction Limit

TRIGGER *rough plane, limiting friction*

BECOMES Use $F \leq \mu R$, and $F = \mu R$ only at limiting motion.

FIRST LINE TO WRITE

$$F_{\max} = \mu R$$

SIMPLEST STRATEGY

1. Find the normal reaction.
2. Read impending direction.
3. Insert friction opposite it.
4. Choose $F = \mu R$ only if limiting.

WORKED MODEL

At impending upward motion, friction acts down the plane.

HARD VARIANTS

1. For equilibrium, friction can be less than μR .
2. Normal reaction changes when a force has a perpendicular component.
3. Check whether motion is up or down the plane before placing friction.

— BOTTOM LINE

Friction has a direction before it has a value.

Quick Recognition Table

WHEN YOU SEE	FIRST LINE TO WRITE
forces on a particle	weight = mg , $R \perp$ surface
force at angle, components	$F_x = F \cos \theta$, $F_y = F \sin \theta$
particle in equilibrium	$\sum F_x = 0$, $\sum F_y = 0$
rough plane, limiting friction	$F_{\max} = \mu R$

Hard Variant Checklist

STRATEGY	CHECK BEFORE FINAL ANSWER
FBD: Free Body Diagram	Tension pulls away from the particle along the string. Normal reaction is perpendicular to the contact surface. Friction opposes actual or impending motion.
RESOLVE: Resolve Forces	If the angle is to the vertical, swap sine/cosine roles. On slopes, axes parallel/perpendicular to plane are usually best. Keep exact trig until the final result.
EQUIL: Equilibrium Equations	Use simultaneous equations when two unknowns appear. If three forces are in equilibrium, a triangle of forces may help. Do not assume $R = mg$ when angled pulls are present.
FRIC: Friction Limit	For equilibrium, friction can be less than μR . Normal reaction changes when a force has a perpendicular component. Check whether motion is up or down the plane before placing friction.

ELITE IGCSE MATHEMATICS
EXPERIENCE NOTES

Newton's Second Law

Dynamics is force-resultant first, then acceleration.

NEWTON'S SECOND LAW · M1 · 07

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01 NET: Net Force

TRIGGER *Newton's second law*

02 TENS: Connected Tension

TRIGGER *connected particles, string*

03 SYS: Whole System

TRIGGER *find acceleration of system*

04 COMBO: Motion Plus Dynamics

TRIGGER *force then distance/time*

BANK EVIDENCE Local pages: 49 problem, 78 answer, 25 notes. Website primary entries: 12. Website linked entries: 55.

01 NET: Net Force

TRIGGER *Newton's second law*

BECOMES Resultant force in a direction equals mass times acceleration.

FIRST LINE TO WRITE

$$\sum F = ma$$

SIMPLEST STRATEGY

1. Name the direction.
2. Enter signed forces.
3. Tie to ma .

WORKED MODEL

■ If right is positive, $P - F = ma$.

HARD VARIANTS

1. Use weight mg , not mass, in vertical force sums.
2. Acceleration sign must match the chosen positive direction.
3. If acceleration is zero, this becomes equilibrium.

— BOTTOM LINE

Only the resultant force equals ma .

02 TENS: Connected Tension

TRIGGER *connected particles, string*

BECOMES Use common acceleration and separate body equations.

FIRST LINE TO WRITE

$$a_A = a_B, \quad \text{same string}$$

SIMPLEST STRATEGY

1. Trace the string.
2. Establish common acceleration.
3. Name tension.
4. Set one equation per body.

WORKED MODEL

For two particles: $P - T = m_1a$, $T - R = m_2a$.

HARD VARIANTS

1. Light string gives the same tension throughout that string.
2. Use whole-system equation to find acceleration quickly, then individual equation for tension.
3. Pulley or slope geometry may reverse signs.

— BOTTOM LINE

Tension is internal to the system but external to each particle.

03 SYS: Whole System

TRIGGER *find acceleration of system*

BECOMES Add bodies together to cancel internal tensions.

FIRST LINE TO WRITE

$$\text{external resultant} = (m_1 + m_2)a$$

SIMPLEST STRATEGY

1. Select the whole moving system.
2. Yield only external forces.
3. Solve for common acceleration.

WORKED MODEL

▮ If two masses move together, $P - R = (m_1 + m_2)a$.

HARD VARIANTS

1. Only include bodies that share the same acceleration.
2. External resistance and weight components remain.
3. Return to a single-body equation for tension.

— BOTTOM LINE

Internal tensions cancel in the whole-system equation.

04 COMBO: Motion Plus Dynamics

TRIGGER *force then distance/time*

BECOMES Find acceleration from forces, then use kinematics.

FIRST LINE TO WRITE

$$\sum F = ma \Rightarrow \text{SUVAT}$$

SIMPLEST STRATEGY

1. Calculate acceleration.
2. Organise initial motion data.
3. Match SUVAT equation.
4. Bring units together.
5. Output requested time/speed/distance.

WORKED MODEL

$$| \quad a = 2, \text{ then } v^2 = u^2 + 2as.$$

HARD VARIANTS

1. If a force stops acting, split the motion into stages.
2. Friction may change direction after motion reverses.
3. Use the acceleration from the correct stage only.

— BOTTOM LINE

Dynamics often supplies the missing SUVAT acceleration.

Practice Page: COMBO

QUESTION TYPE Dynamics plus kinematics

A pulled particle starts from rest; find its speed after moving 10 m.

COMMON TRAP Using force equations after acceleration changes.

Quick Recognition Table

WHEN YOU SEE	FIRST LINE TO WRITE
Newton's second law	$\sum F = ma$
connected particles, string	$a_A = a_B$, same string
find acceleration of system	external resultant = $(m_1 + m_2)a$
force then dis- tance/time	$\sum F = ma \Rightarrow$ SUVAT

Hard Variant Checklist

STRATEGY	CHECK BEFORE FINAL ANSWER
NET: Net Force	Use weight mg , not mass, in vertical force sums. Acceleration sign must match the chosen positive direction. If acceleration is zero, this becomes equilibrium.
TENS: Connected Tension	Light string gives the same tension throughout that string. Use whole-system equation to find acceleration quickly, then individual equation for tension. Pulley or slope geometry may reverse signs.
SYS: Whole System	Only include bodies that share the same acceleration. External resistance and weight components remain. Return to a single-body equation for tension.
COMBO: Motion Plus Dynamics	If a force stops acting, split the motion into stages. Friction may change direction after motion reverses. Use the acceleration from the correct stage only.

ELITE IGCSE MATHEMATICS
EXPERIENCE NOTES

Resolving Forces Inclined Planes

Slope questions become straight when axes run along and normal to the plane.

RESOLVING FORCES, INCLINED PLANES · M1 · 08

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01 AXES: Slope Axes

TRIGGER *inclined plane*

02 NORM: Normal Reaction

TRIGGER *reaction on inclined plane*

03 SLIDE: Sliding Equation

TRIGGER *acceleration on slope*

04 LIMIT: Limiting Friction On Slope

TRIGGER *rough inclined plane, about to move*

BANK EVIDENCE Local pages: 43 problem, 68 answer, 19 notes. Website primary entries: 19. Website linked entries: 29.

01 AXES: Slope Axes

TRIGGER *inclined plane*

BECOMES Resolve parallel and perpendicular to the plane.

FIRST LINE TO WRITE

$mg \sin \theta$ down slope, $mg \cos \theta$ into plane

SIMPLEST STRATEGY

1. Align axes with the plane.
2. Xmark weight components.
3. Equation parallel.
4. Second equation perpendicular.

WORKED MODEL

On a 30° slope, the down-slope component is $mg \sin 30^\circ$.

HARD VARIANTS

1. The normal reaction is perpendicular to the plane.
2. If the angle is given to the vertical, redraw the triangle.
3. Keep signs according to up/down slope choice.

— BOTTOM LINE

Slope axes remove unnecessary diagonal forces.

02 NORM: Normal Reaction

TRIGGER *reaction on inclined plane*

BECOMES Use perpendicular balance because acceleration perpendicular to the plane is zero.

FIRST LINE TO WRITE

$$\sum F_{\perp} = 0$$

SIMPLEST STRATEGY

1. Name perpendicular axis.
2. Oppose into/out of plane components.
3. Reaction is unknown.
4. Make equation.

WORKED MODEL

▮ If no other perpendicular force acts, $R = mg \cos \theta$.

HARD VARIANTS

1. Angled pulls or pushes change R .
2. No perpendicular acceleration does not mean no perpendicular forces.
3. Friction depends on this R , so find it first.

— BOTTOM LINE

The normal reaction is found perpendicular to the surface.

03 SLIDE: Sliding Equation

TRIGGER *acceleration on slope*

BECOMES Resolve along the plane and use $\Sigma F = ma$.

FIRST LINE TO WRITE

$$\Sigma F_{\parallel} = ma$$

SIMPLEST STRATEGY

1. Select positive direction.
2. List along-plane forces.
3. Insert signs.
4. Do ma .
5. Evaluate acceleration.

WORKED MODEL

Down a smooth slope: $mg \sin \theta = ma$, so $a = g \sin \theta$.

HARD VARIANTS

1. Friction acts opposite motion or impending motion.
2. If motion is up the slope, weight component and friction may both act down slope.
3. Use SUVAT after acceleration is found.

— BOTTOM LINE

The along-plane equation drives the motion.

04 LIMIT: Limiting Friction On Slope

TRIGGER *rough inclined plane, about to move*

BECOMES Set friction to μR only at the limiting case.

FIRST LINE TO WRITE

$$F = \mu R$$

SIMPLEST STRATEGY

1. Locate impending motion.
2. Insert friction opposite it.
3. Make $F = \mu R$.
4. Include weight component.
5. Tidy inequality/equality.

WORKED MODEL

▮ About to slide down: friction acts up the slope.

HARD VARIANTS

1. For rest, friction may be less than μR .
2. If an applied force acts, it may change both R and the limiting friction.
3. Check whether the question asks greatest or least force.

— BOTTOM LINE

Limiting friction is a threshold, not a default.

Quick Recognition Table

WHEN YOU SEE	FIRST LINE TO WRITE
inclined plane	$mg \sin \theta$ down slope, $mg \cos \theta$ into plane
reaction on inclined plane	$\sum F_{\perp} = 0$
acceleration on slope	$\sum F_{\parallel} = ma$
rough inclined plane, about to move	$F = \mu R$

Hard Variant Checklist

STRATEGY	CHECK BEFORE FINAL ANSWER
AXES: Slope Axes	The normal reaction is perpendicular to the plane. If the angle is given to the vertical, redraw the triangle. Keep signs according to up/down slope choice.
NORM: Normal Reaction	Angled pulls or pushes change R . No perpendicular acceleration does not mean no perpendicular forces. Friction depends on this R , so find it first.
SLIDE: Sliding Equation	Friction acts opposite motion or impending motion. If motion is up the slope, weight component and friction may both act down slope. Use SUVAT after acceleration is found.
LIMIT: Limiting Friction On Slope	For rest, friction may be less than μR . If an applied force acts, it may change both R and the limiting friction. Check whether the question asks greatest or least force.

ELITE IGCSE MATHEMATICS
EXPERIENCE NOTES

Momentum, Impulse & Collisions

*Momentum questions are bookkeeping: direction, before/after,
and impulse.*

MOMENTUM, IMPULSE & COLLISIONS · M1 · 09

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01 MOM: Conserve Momentum

TRIGGER *collision, before and after*

02 IMP: Impulse Change

TRIGGER *impulse, change in momentum*

03 COLL: Collision Pair

TRIGGER *two particles collide*

04 FORCE: Impulse From Force

TRIGGER *constant force for time, force-time graph*

BANK EVIDENCE Local pages: 29 problem, 51 answer, 9 notes. Website primary entries: 18. Website linked entries: 22.

01 MOM: Conserve Momentum

TRIGGER *collision, before and after*

BECOMES Total momentum before equals total momentum after, in one chosen direction.

FIRST LINE TO WRITE

$$\sum mu = \sum mv$$

SIMPLEST STRATEGY

1. Mark positive direction.
2. Order before and after.
3. Multiply mass by velocity.
4. Equate totals.
5. Negative signs for opposite direction.
6. Tidy unknown velocity.

WORKED MODEL

$$2(5) + 3(-1) = 2v_1 + 3v_2.$$

HARD VARIANTS

1. Use velocities, not speeds, inside the equation.
2. External impulse must be absent for conservation.
3. Check if particles coalesce and share one final velocity.

— BOTTOM LINE

Momentum conservation is signed.

02 IMP: Impulse Change

TRIGGER *impulse, change in momentum*

BECOMES Impulse equals final momentum minus initial momentum.

FIRST LINE TO WRITE

$$I = m(v - u)$$

SIMPLEST STRATEGY

1. Identify direction.
2. Multiply final velocity.
3. Prepare initial momentum.
4. Use final minus initial.
5. Label N s.
6. State direction.
7. Evaluate.

WORKED MODEL

■ If $u = 4$ and $v = -2$, then $I = m(-2 - 4)$.

HARD VARIANTS

1. The impulse on the other body is equal and opposite.
2. Units are N s or kg m s^{-1} .
3. If a force-time graph is given, impulse is area.

— BOTTOM LINE

Impulse is a signed change.

03 COLL: Collision Pair

TRIGGER *two particles collide*

BECOMES Use momentum plus any given collision relation.

FIRST LINE TO WRITE

| momentum equation + second relation

SIMPLEST STRATEGY

1. Choose direction.
2. Organise before/after table.
3. Link with momentum.
4. Link with given condition.
5. Solve simultaneous equations.
6. Decide physical root.
7. End with speeds/directions.

WORKED MODEL

| If they move together, set $v_1 = v_2$ after impact.

HARD VARIANTS

1. For coalescence, both final velocities are equal.
2. If a rebound happens, one velocity changes sign.
3. Check that post-collision directions match the signs you report.

— BOTTOM LINE

One equation is rarely enough for two final velocities.

04 FORCE: Impulse From Force

TRIGGER *constant force for time, force-time graph*

BECOMES Use impulse as force times time or area under force-time graph.

FIRST LINE TO WRITE

$$I = Ft \quad \text{or} \quad I = \text{area}$$

SIMPLEST STRATEGY

1. Find the time interval.
2. Obtain force or graph area.
3. Relate to $m(v - u)$.
4. Calculate unknown.
5. Express direction.

WORKED MODEL

▮ A force 6 N for 0.4 s gives impulse 2.4 N s.

HARD VARIANTS

1. For triangular force graphs, use triangle area.
2. Direction of force controls sign of impulse.
3. Average force is impulse divided by time.

— BOTTOM LINE

Impulse is the area under a force-time graph.

Quick Recognition Table

WHEN YOU SEE	FIRST LINE TO WRITE
collision, before and after	$\sum mu = \sum mv$
impulse, change in momentum	$I = m(v - u)$
two particles collide	momentum equation + second relation
constant force for time, force-time graph	$I = Ft$ or $I = \text{area}$

Hard Variant Checklist

STRATEGY	CHECK BEFORE FINAL ANSWER
MOM: Conserve Momentum	Use velocities, not speeds, inside the equation. External impulse must be absent for conservation. Check if particles coalesce and share one final velocity.
IMP: Impulse Change	The impulse on the other body is equal and opposite. Units are N s or kg m s^{-1} . If a force-time graph is given, impulse is area.
COLL: Collision Pair	For coalescence, both final velocities are equal. If a rebound happens, one velocity changes sign. Check that post-collision directions match the signs you report.
FORCE: Impulse From Force	For triangular force graphs, use triangle area. Direction of force controls sign of impulse. Average force is impulse divided by time.

ELITE IGCSE MATHEMATICS
EXPERIENCE NOTES

Moments

Moments questions become calm when you choose the pivot that deletes the worst unknown.

MOMENTS · M1 · 10

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01 PIVOT: Choose Pivot

TRIGGER *take moments about*

02 REACT: Find Reactions

TRIGGER *supports, reactions*

03 TILT: Tilting Limit

TRIGGER *on point of tilting, just lifts*

04 CENTRE: Centre Of Mass

TRIGGER *uniform rod, midpoint, centre*

BANK EVIDENCE Local pages: 39 problem, 57 answer, 13 notes. Website primary entries: 18. Website linked entries: 18.

01 PIVOT: Choose Pivot

TRIGGER *take moments about*

BECOMES Take moments about a point that removes an unknown reaction or tension.

FIRST LINE TO WRITE

$$\sum M_{\text{clockwise}} = \sum M_{\text{anticlockwise}}$$

SIMPLEST STRATEGY

1. Pick the pivot.
2. Ignore forces through pivot.
3. Value each perpendicular distance.
4. Orient clockwise/anticlockwise.
5. Tidy equation.

WORKED MODEL

▮ Taking moments about A removes the reaction at A.

HARD VARIANTS

1. Use perpendicular distance to the line of action.
2. Weight of a uniform rod acts at its midpoint.
3. For angled forces, use perpendicular component or perpendicular distance.

— BOTTOM LINE

A good pivot deletes one unknown.

02 REACT: Find Reactions

TRIGGER *supports, reactions*

BECOMES Use vertical equilibrium plus a moment equation.

FIRST LINE TO WRITE

$$R_A + R_B = \text{total weight}$$

SIMPLEST STRATEGY

1. Record upward reactions.
2. Equate vertical forces.
3. Apply one moment equation.
4. Calculate reactions.
5. Test by substitution.

WORKED MODEL

▮ $R_A + R_B = 50g$, then moments gives one reaction.

HARD VARIANTS

1. Use mg for each mass.
2. If a support is at a pivot, its moment about that point is zero.
3. Check reactions are non-negative unless the support loses contact.

— BOTTOM LINE

Reactions are forces, so they belong in force balance and moments.

03 TILT: Tilting Limit

TRIGGER *on point of tilting, just lifts*

BECOMES At tilting, the reaction at the lifting support is zero.

FIRST LINE TO WRITE

$$R_{\text{lifting support}} = 0$$

SIMPLEST STRATEGY

1. Tell which pivot remains.
2. Ignore reaction at pivot in moments.
3. Let other support reaction be zero.
4. Take moments about pivot.

WORKED MODEL

■ On the point of tilting about C, the reaction at D is zero.

HARD VARIANTS

1. Greatest/least mass decides which end is about to lift.
2. Draw the pivot before writing equations.
3. Use equality at the limiting case, not inequality.

— BOTTOM LINE

Tilting means one support has just lost contact.

04 CENTRE: Centre Of Mass

TRIGGER *uniform rod, midpoint, centre*

BECOMES Place the weight at the centre of mass before taking moments.

FIRST LINE TO WRITE

| uniform rod weight at midpoint

SIMPLEST STRATEGY

1. Check if body is uniform.
2. Establish midpoint/centre.
3. Name the weight.
4. Take distance from pivot.
5. Reuse in moments.
6. End with units.

WORKED MODEL

| A uniform 6 m rod has weight acting 3 m from either end.

HARD VARIANTS

1. Non-uniform rods may give the centre distance as x .
2. If a particle is attached, its weight acts at its own point, not the rod midpoint.
3. Distances must be from the chosen pivot.

— BOTTOM LINE

Uniform means midpoint weight.

Quick Recognition Table

WHEN YOU SEE	FIRST LINE TO WRITE
take moments about supports, reactions	$\sum M_{\text{clockwise}} = \sum M_{\text{anticlockwise}}$
on point of tilting, just lifts	$R_A + R_B = \text{total weight}$
uniform rod, midpoint, centre	$R_{\text{lifting support}} = 0$
	uniform rod weight at midpoint

Hard Variant Checklist

STRATEGY	CHECK BEFORE FINAL ANSWER
PIVOT: Choose Pivot	Use perpendicular distance to the line of action. Weight of a uniform rod acts at its midpoint. For angled forces, use perpendicular component or perpendicular distance.
REACT: Find Reactions	Use mg for each mass. If a support is at a pivot, its moment about that point is zero. Check reactions are non-negative unless the support loses contact.
TILT: Tilting Limit	Greatest/least mass decides which end is about to lift. Draw the pivot before writing equations. Use equality at the limiting case, not inequality.
CENTRE: Centre Of Mass	Non-uniform rods may give the centre distance as x . If a particle is attached, its weight acts at its own point, not the rod midpoint. Distances must be from the chosen pivot.